

Mapping and Navigating in a Hectic World

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Who is Alibaba



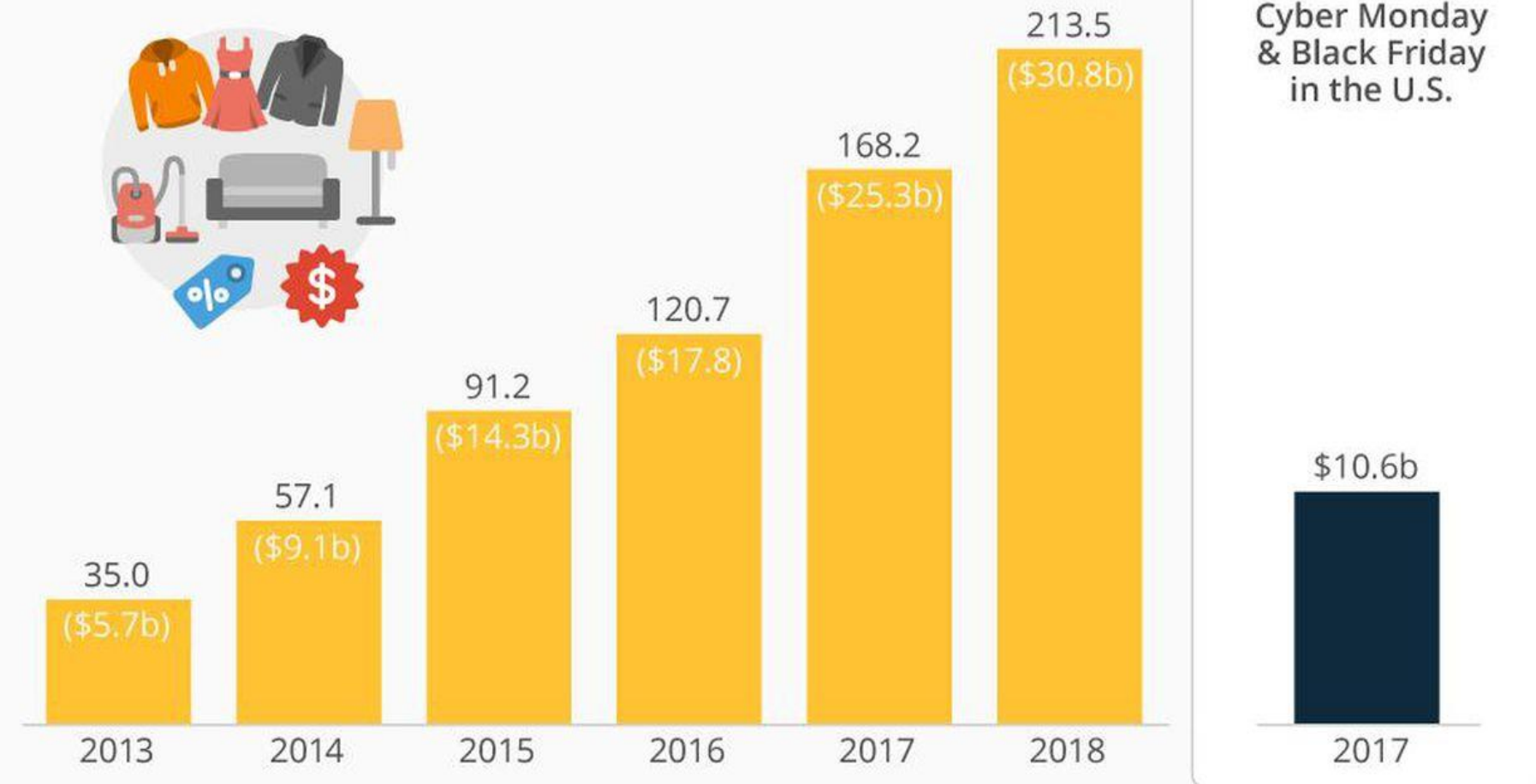
Alibaba @ Hangzhou



Alibaba in E-commerce

Singles' Day Sets Another Sales Record

GMV for Alibaba on Singles' Day compared to Black Friday & Cyber Monday* (in RMB)



* Gross merchandise volume; U.S. figure for Black Friday and Cyber Monday is total e-commerce sales.
Source: Alibaba via Techcrunch



@StatistaCharts

Alibaba Eco-System



Who is **Amap** (AutoNavi)?

No.1 Mapping and Navigation Company in China



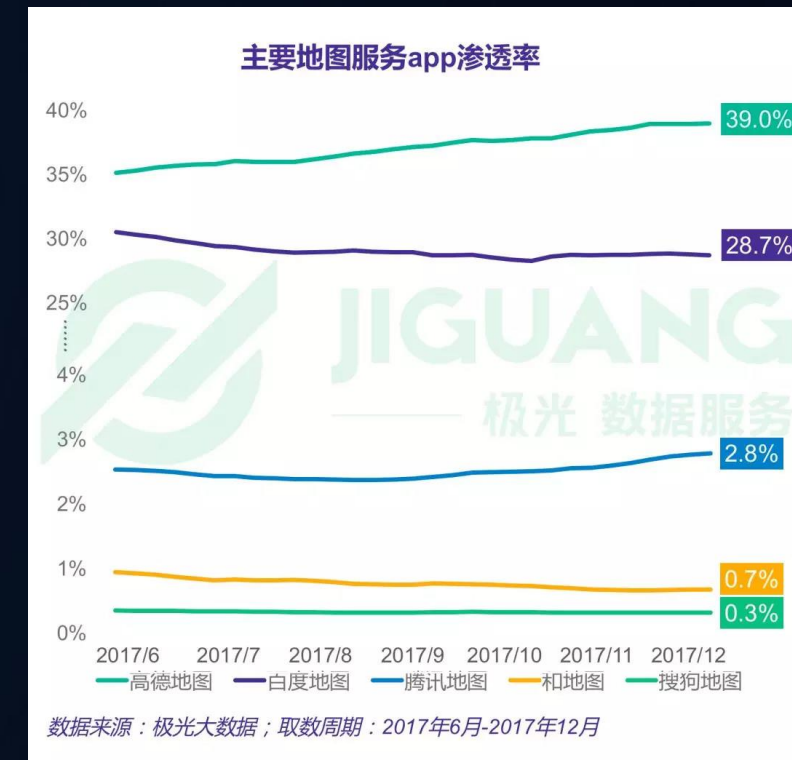
426M active users
(QuestMobile 2018/07)



8.2M km roads



70M POI



← **Amap**

Who is **Amap** (AutoNavi)?

No.1 Map in China and No.1 Human-Location Relations



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People & Activities



Locations & Places

Who is **Amap** (AutoNavi)?

No.1 Map in China and No.1 Human-Location Relations



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8.2M km roads



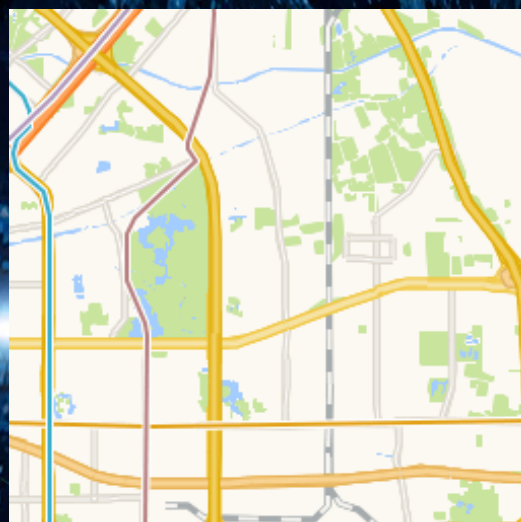
70M POI



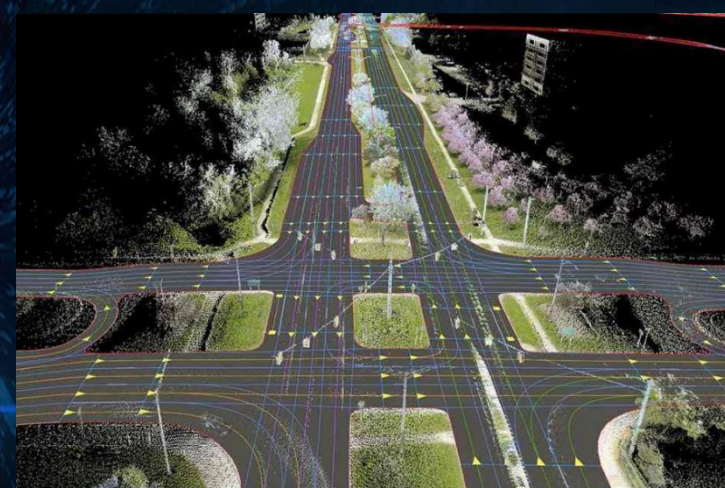
..... Upper Body

..... Lower Body

Computer Vision @ Amap

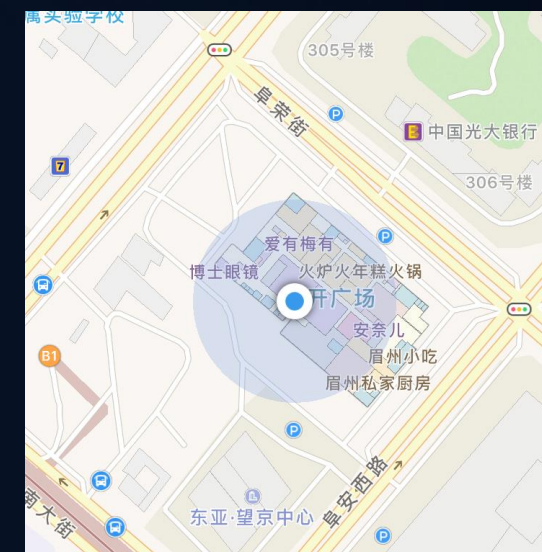


SD Map



HD Map

Mapping Automation



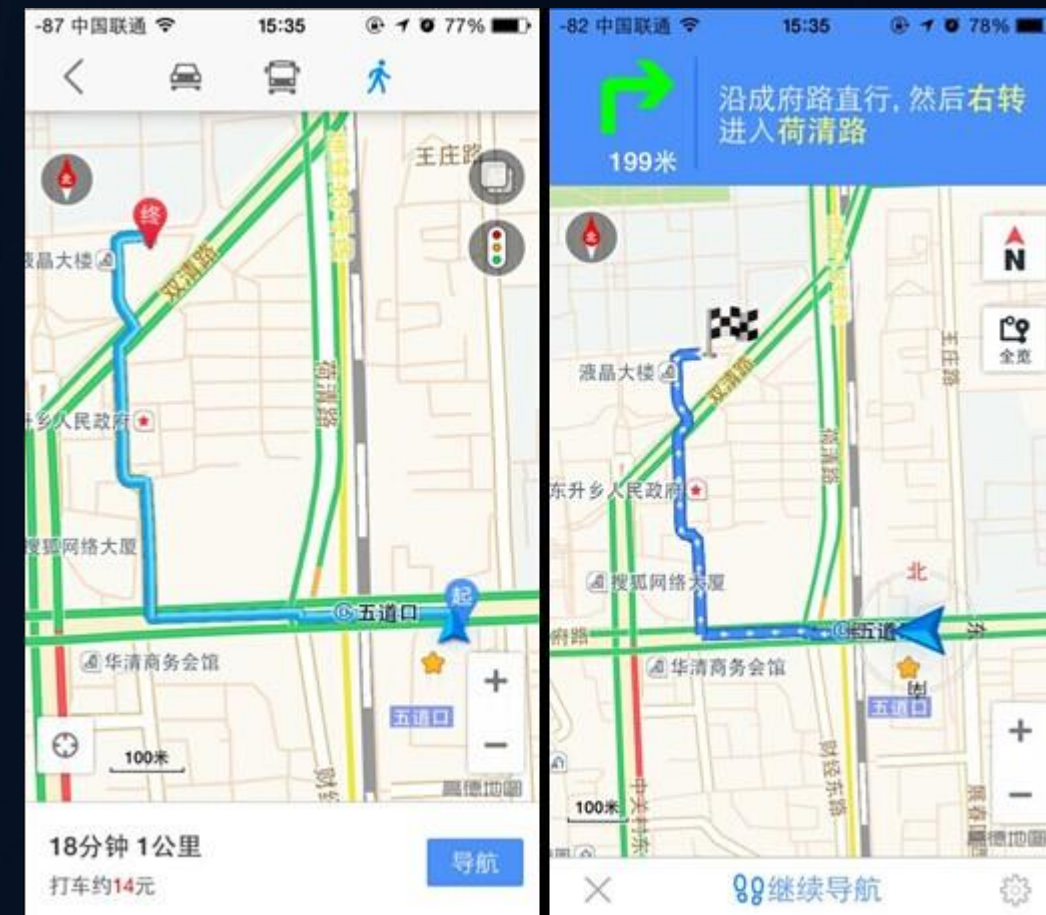
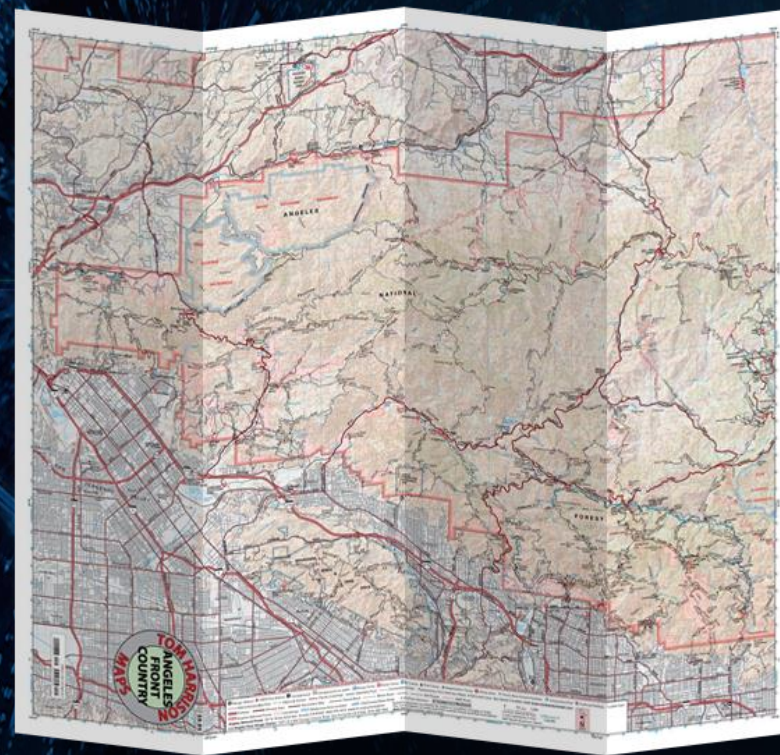
Location



AR Navigation

“Easy” Navigation

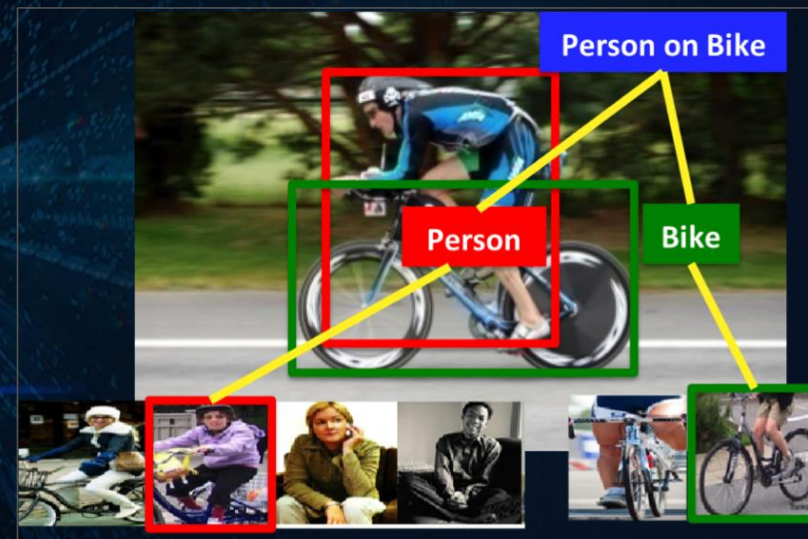
Under the Hood



Basic Pipeline of Map Production



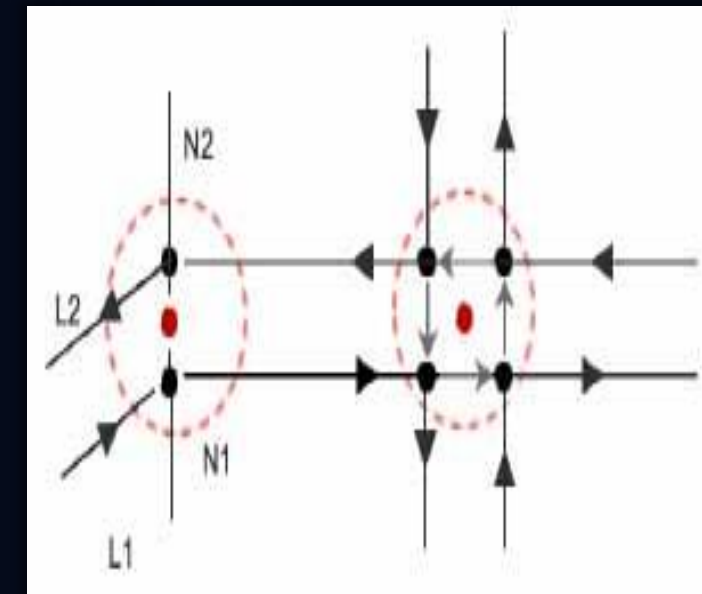
Data
Acquisition



Automatic
Recognition



Fusion &
Human Editing



Map Database
& Service

Auto-Generation of Road Data



Detection → Classification → Sign & Text Recognition

Auto-Generation of Road Data



a. "not allowed"

b. long-distance coach

c. 2:00-5:00

1. Detection & Classification

2. Parsing & Text Reading

Why is Mapping (still) a Problem?



Map is a “deep” business



... and it's hard in a hectic world

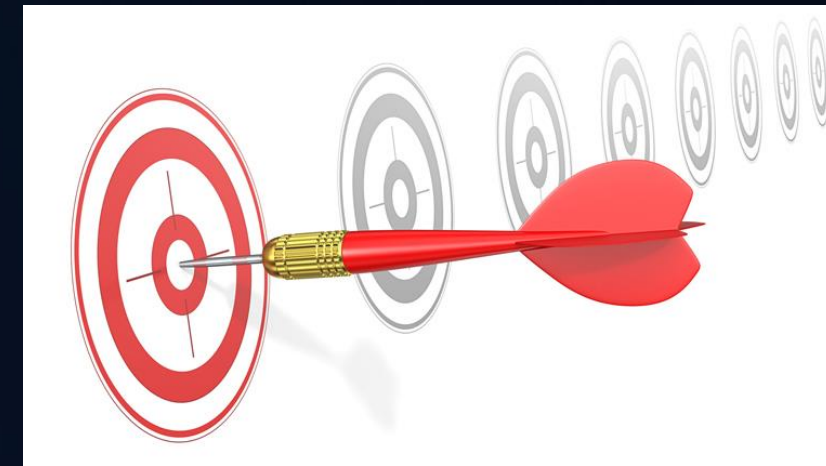
Mapping is a “Deep” Business



Scale (and diversity)



Complexity (and specification)



Accuracy (and updating)



Cost (and data quality)

Challenge: Data Quality



Challenge: Data Quality



Distortion
Reflection
Occlusion

Resolution
Compression
Image quality

... ..

Auto Calibration in the Wild



Unknown camera: focal length, distortion, height and pose
Solution: combine multiple data sources

Image Enhancement

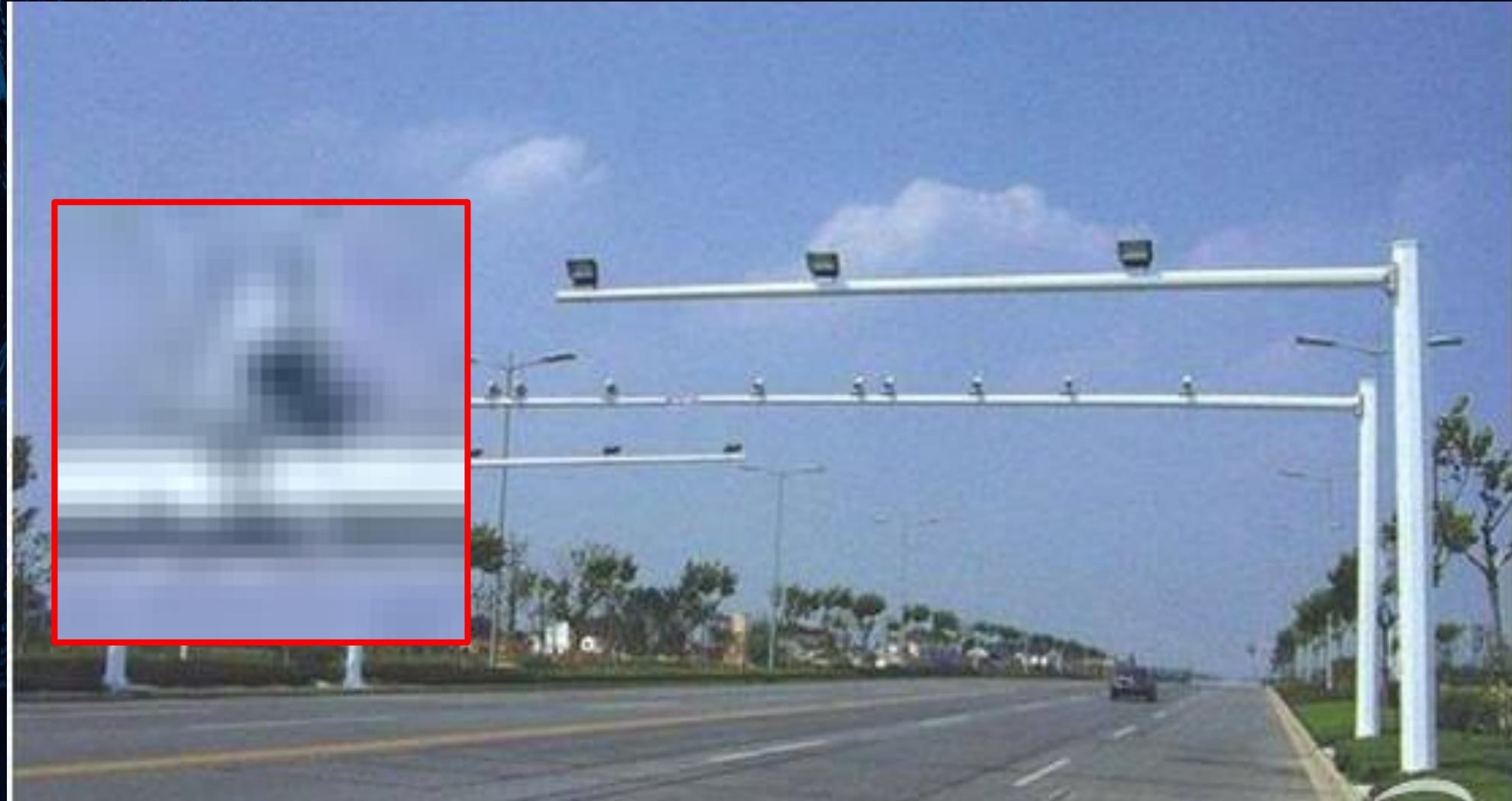


Original

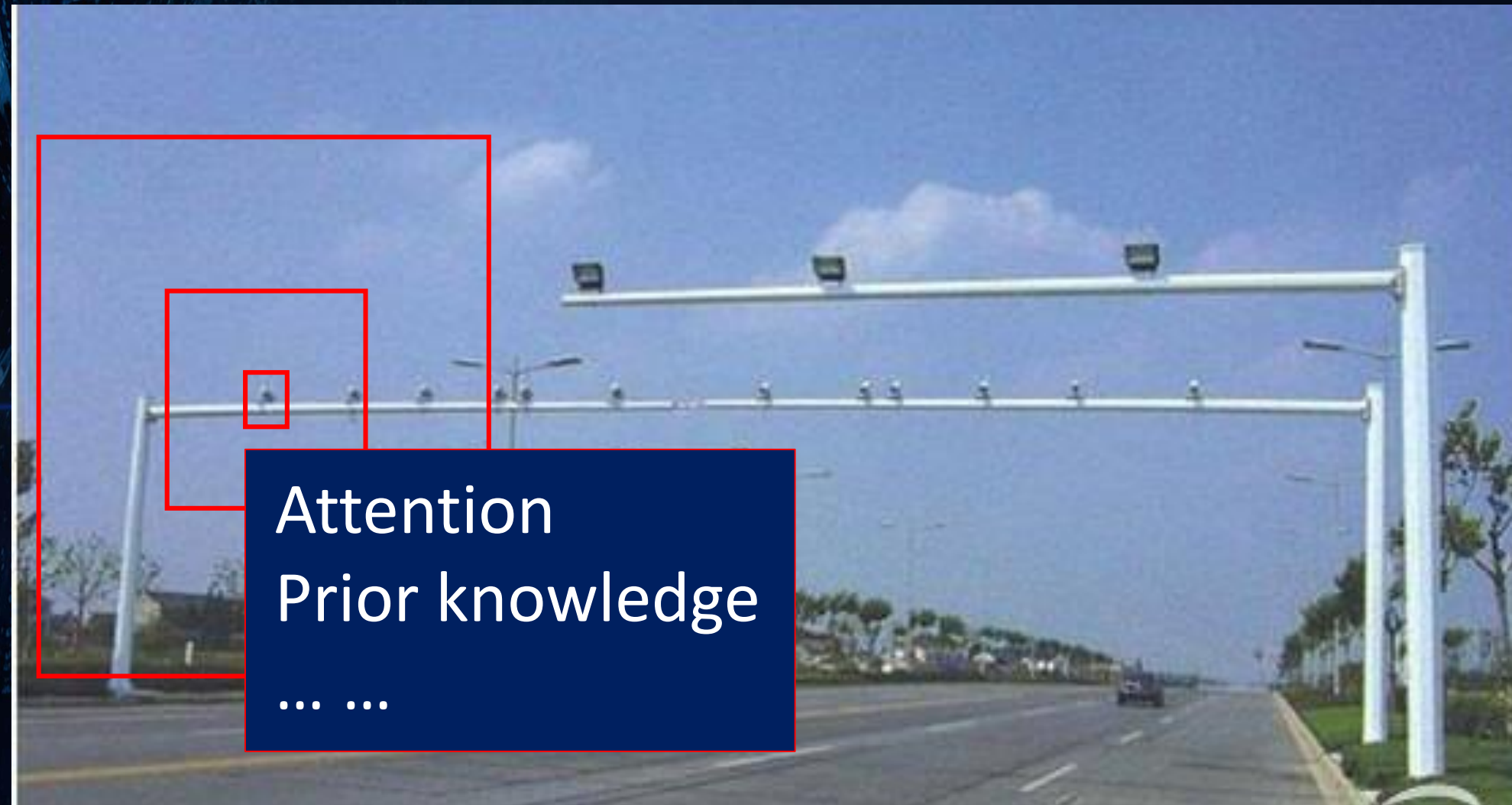
Challenge: Small Objects



Challenge: Small Objects



Challenge: Small Objects

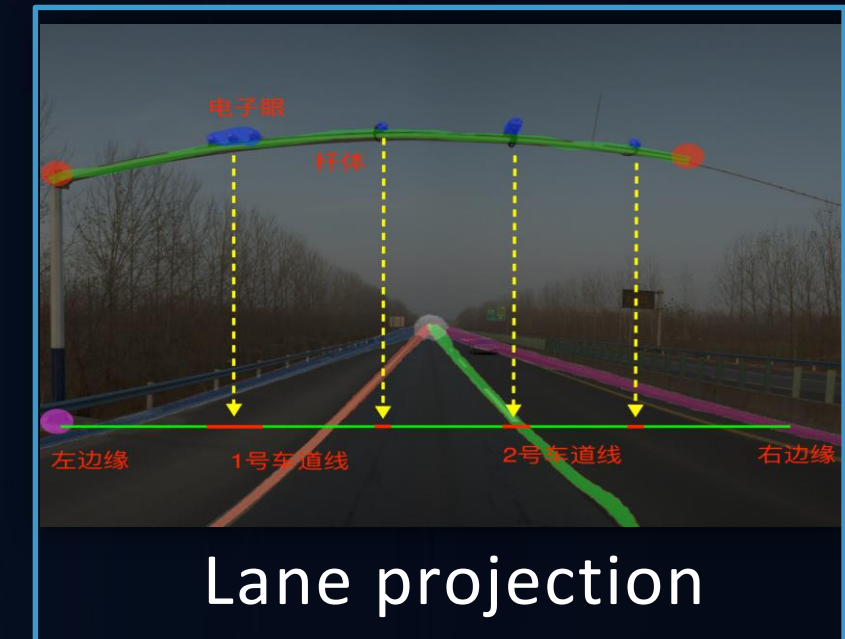
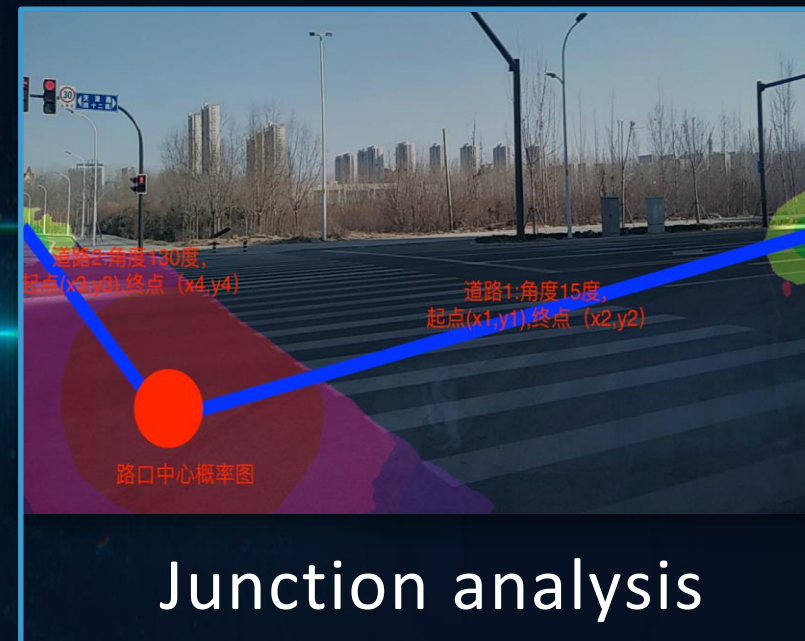
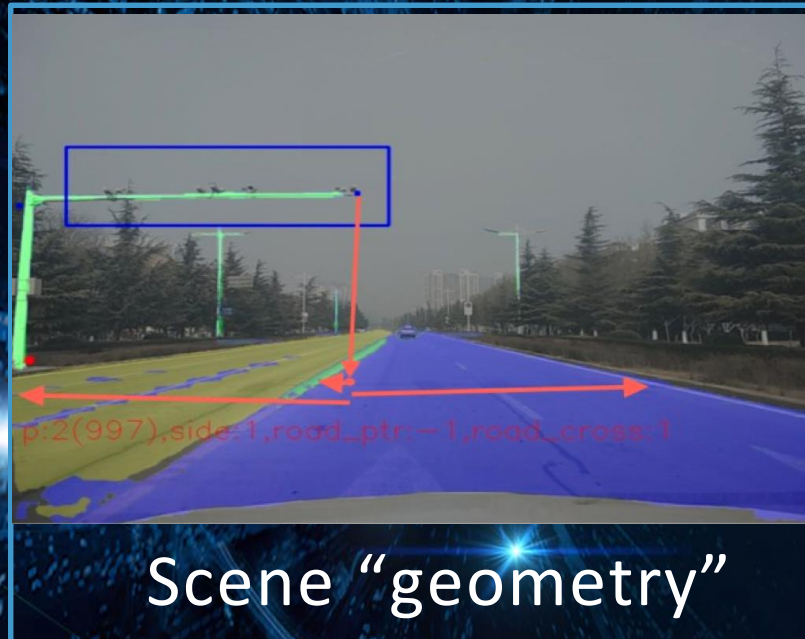


Challenge: Scene Complexity



Does this electronic eye belong to the current road? Which lane?

Challenge: Scene Complexity



- Object detection
- Semantic segmentation
- Scene understanding
- Geometry and calibration

Challenge: Scene Complexity



Challenge: Scene Complexity



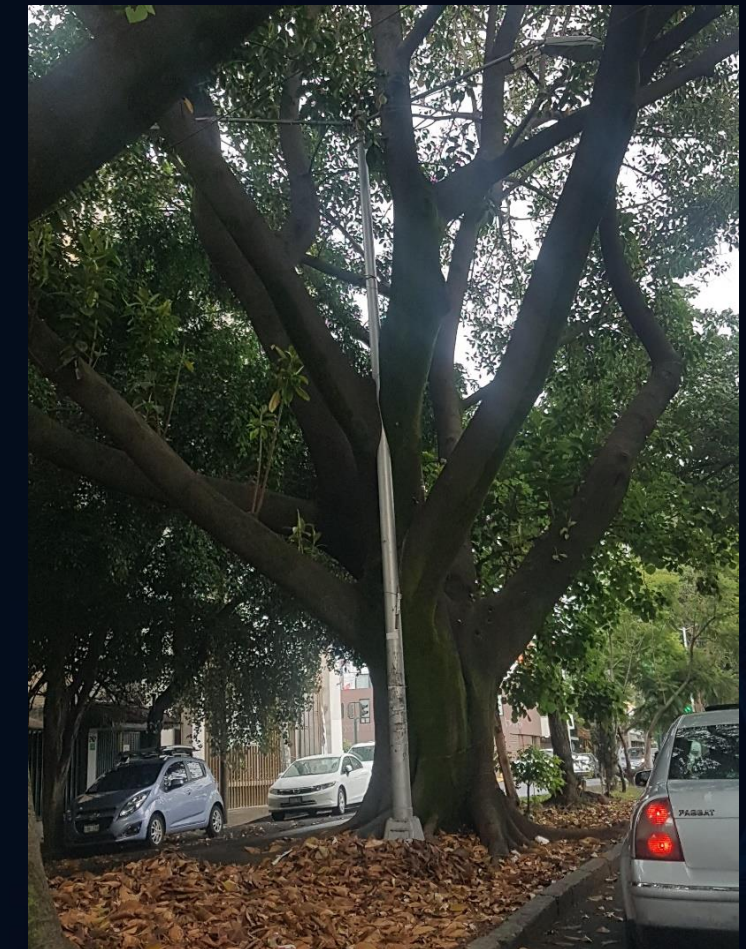
Challenge: Ambiguity



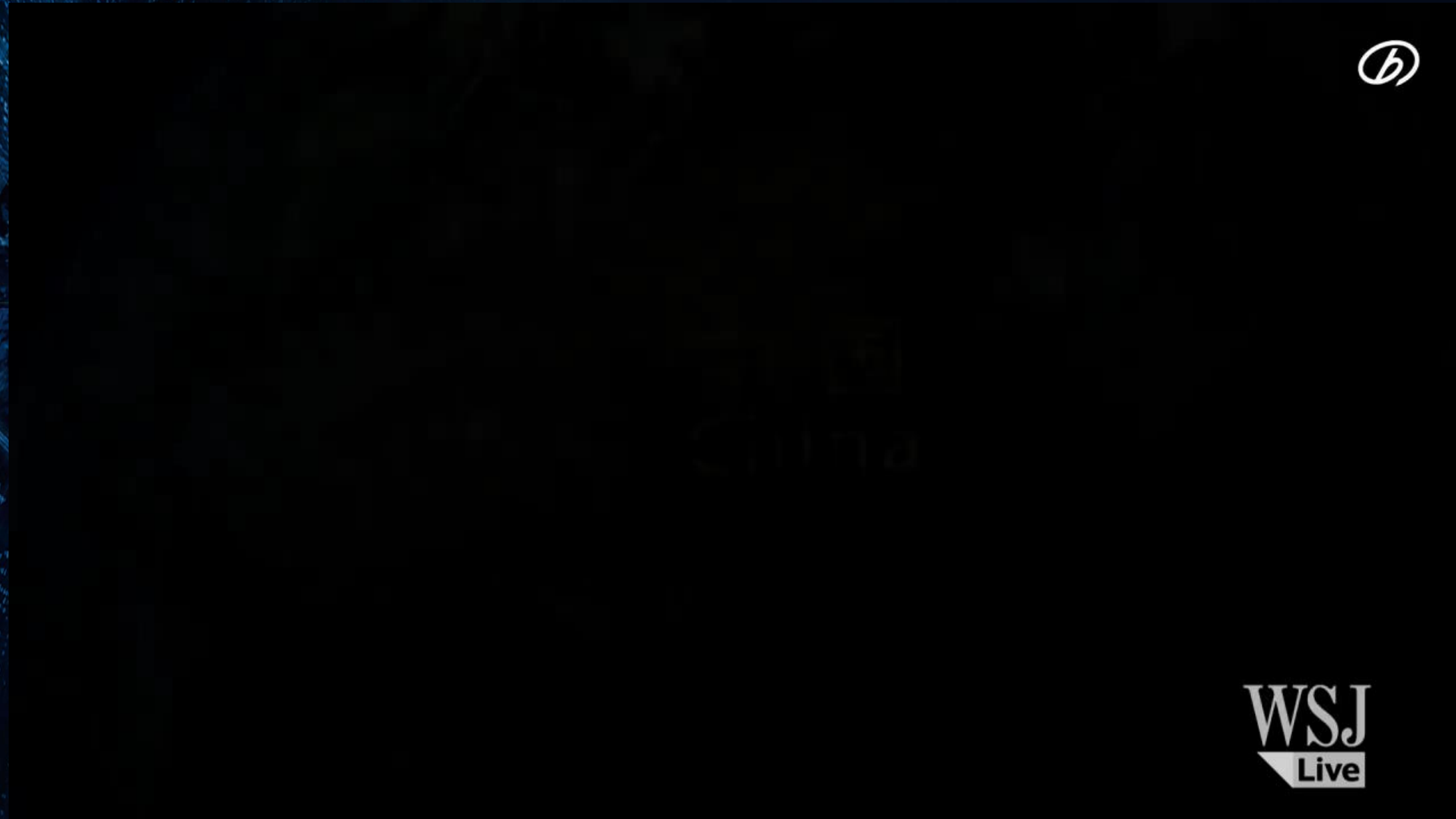
Challenge: Ambiguity



Challenge: Ambiguity



Challenge: Frequent Changes



Change Detection



- Object matching
Feature + deep learning
- Context matching
Segmentation + relations
- Scene matching
Feature + deep learning

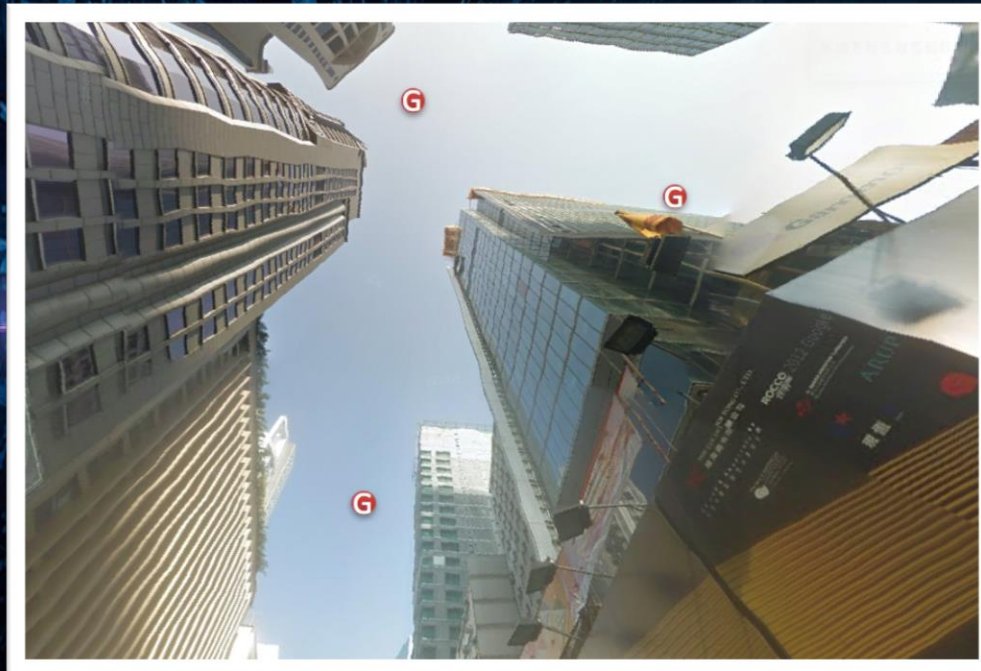
Challenge: Ambiguity

Can cars turn here?

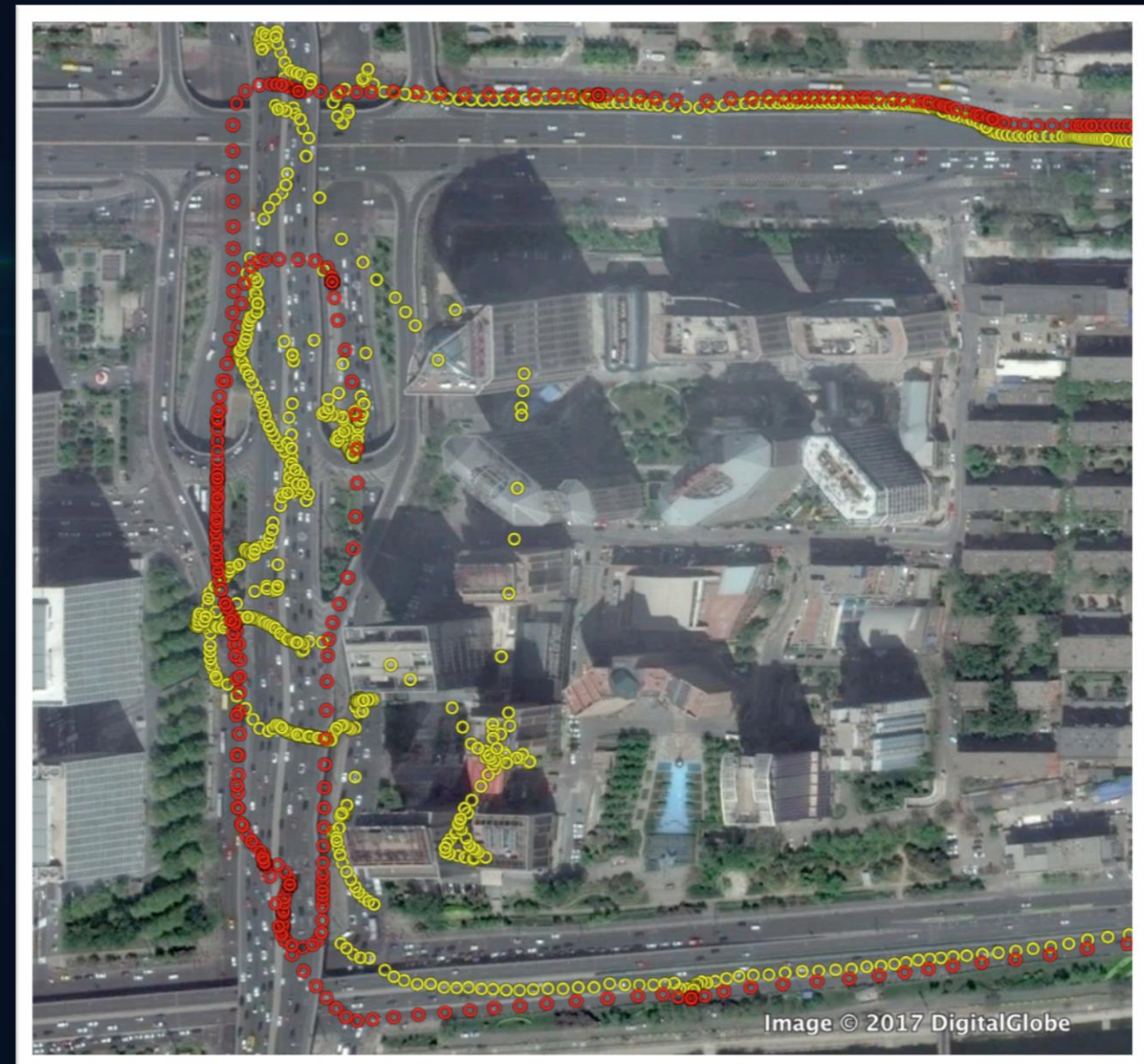
Solution: Vision + GPS



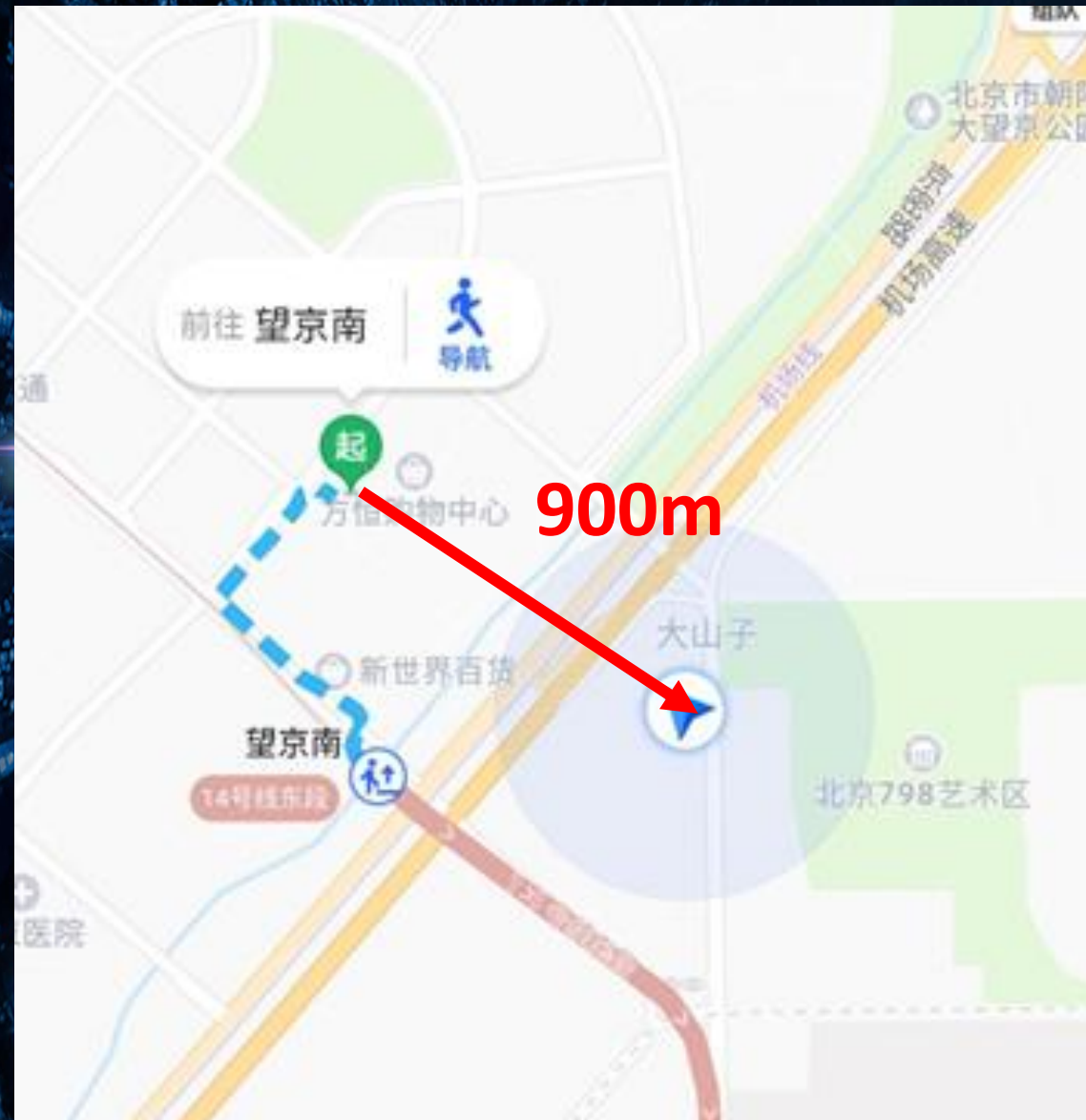
Challenge: Location



Urban Canyon



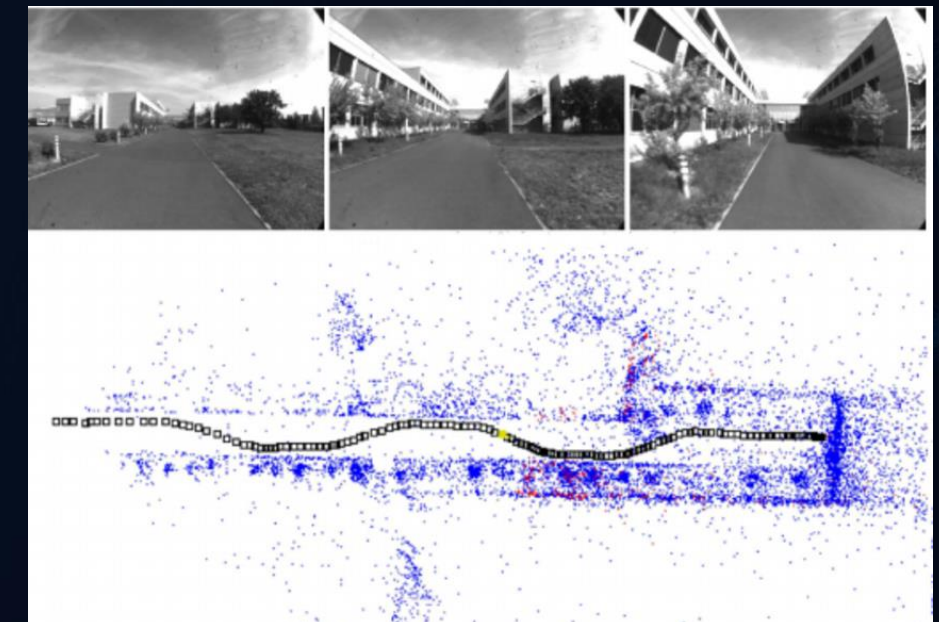
Challenge: Location



WiFi



Vision



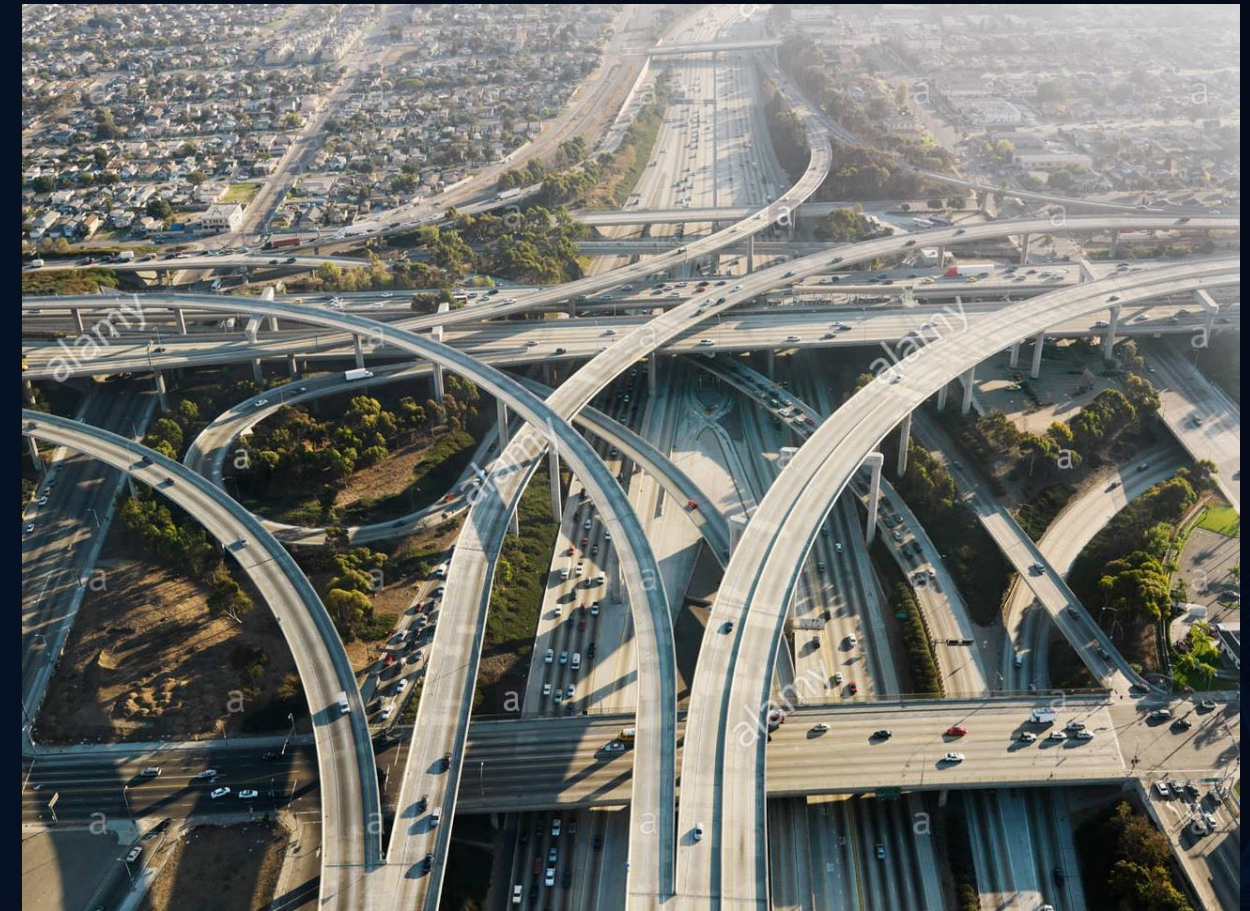
How We Solve Problems in Practice

- Data quality, including annotation
- Data quantity, esp. failure cases
- Iterative improvements (and leaps)
- Combining algorithms from multiple angles
- Human-computer collaboration

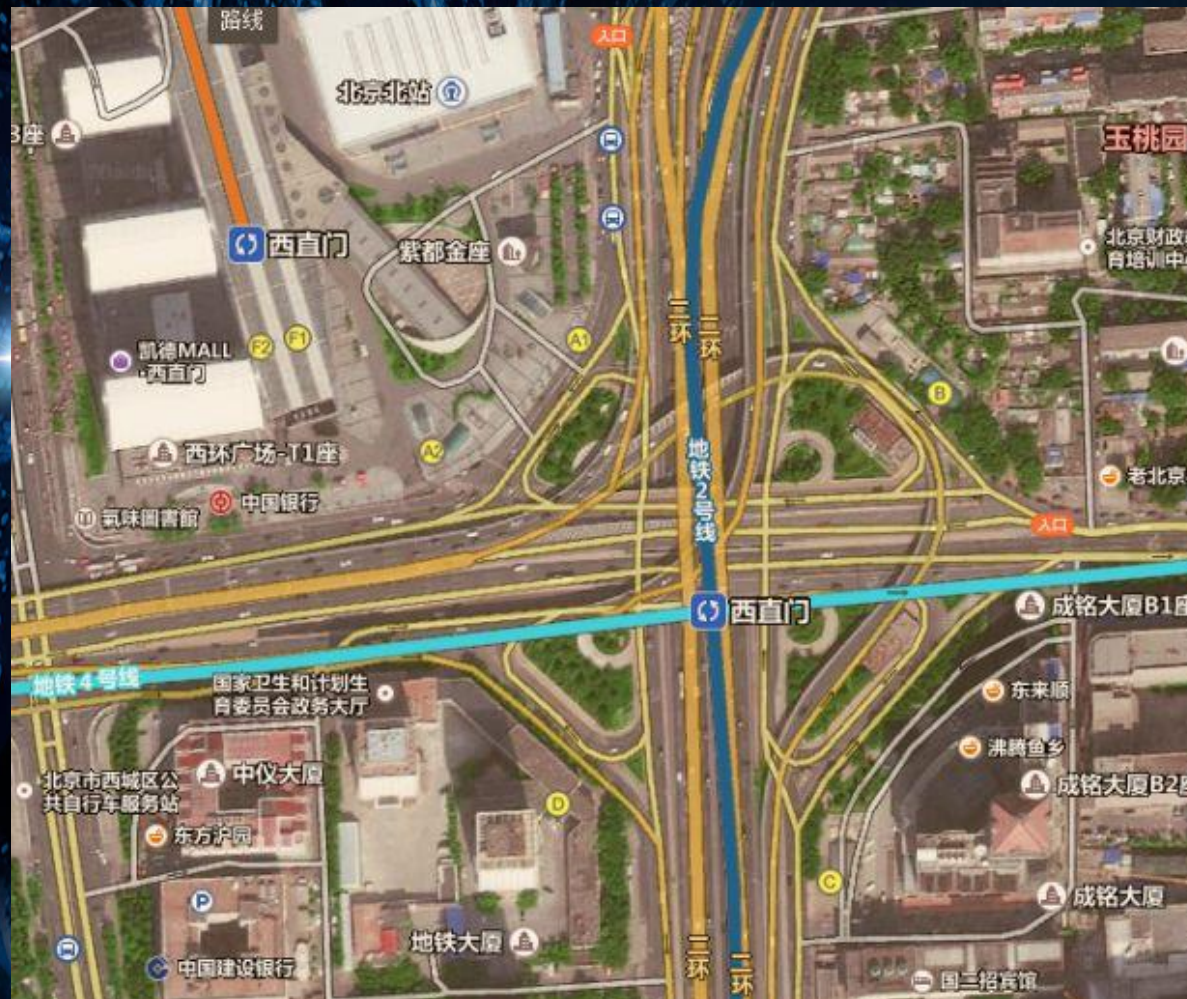
Still, Reality Can Beat You



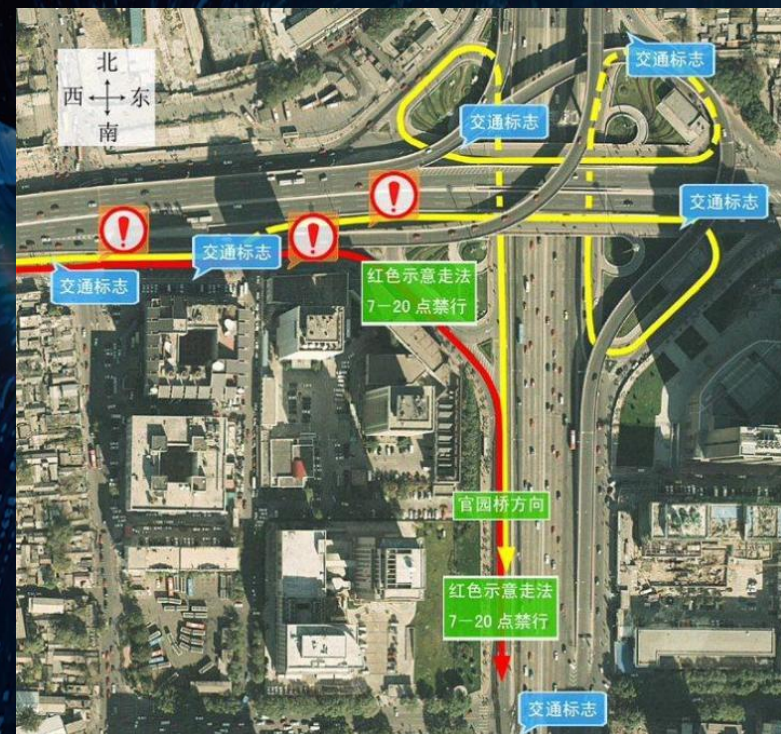
Still, Reality Can Beat You



Still, Reality Can Beat You

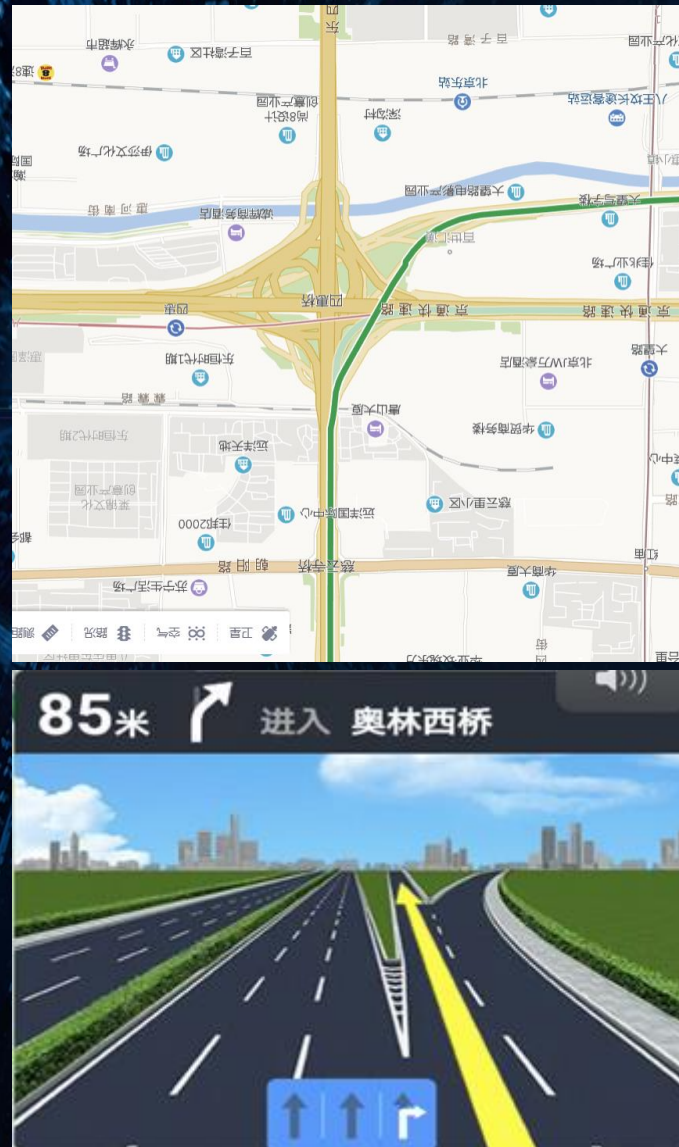


Next-Gen Navigation

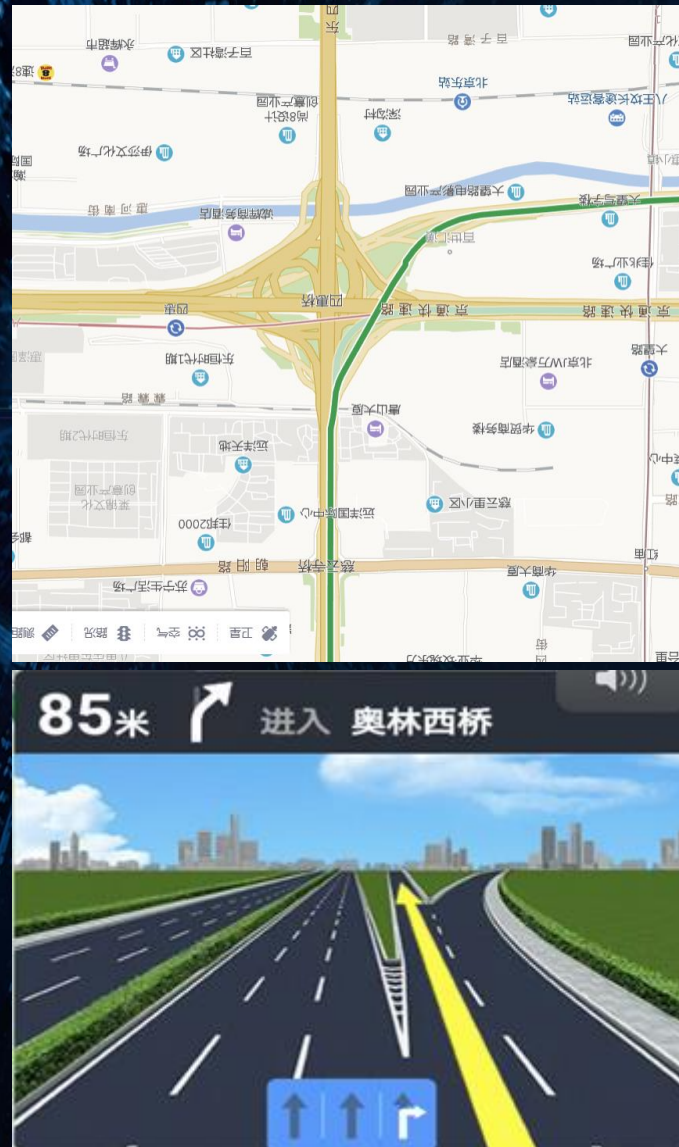


- Accurate map
- Accurate location
- “Easy” directions

Abstract vs WYSIWYG



Abstract vs WYSIWYG



AR Navigation



Launched April 2019

AR Navigation

AR导航 vs 传统导航
更好的解决了哪些用户痛点？

Challenge: Minimal Sensing

UBER ATC

Top mounted lidar units provide a 360° 3-dimensional scan of the environment.

Forward facing camera array focus both close and far field, watching for breaking vehicles, crossing pedestrians, traffic lights, and signage.



Front, rear, and wing mounted lidar modules aide in the detection of obstacles in close proximity to the vehicle as well as smaller ones that can get lost in blind spots.

Side and rear facing stereo camera pairs work in collaboration to construct a continuous view of the vehicle's surrounding.

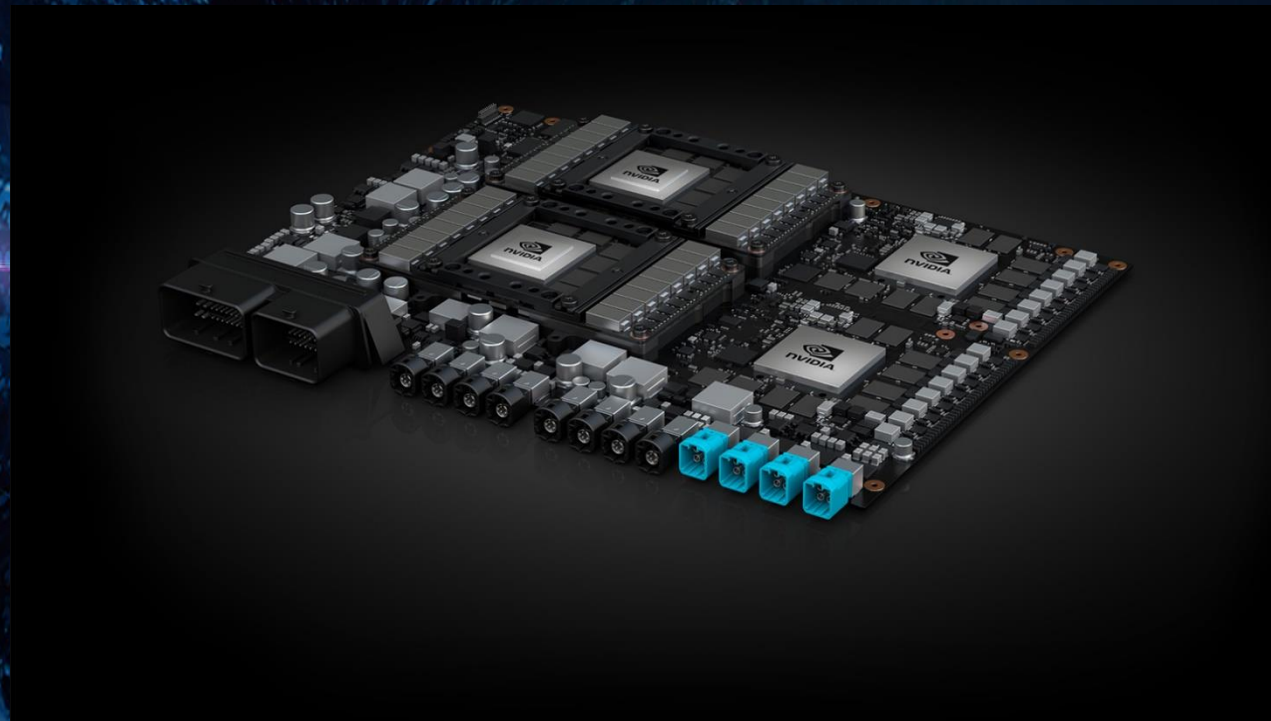
Roof and trunk mount antennae provide G positioning and wireless data capabilities.

360° radar coverage

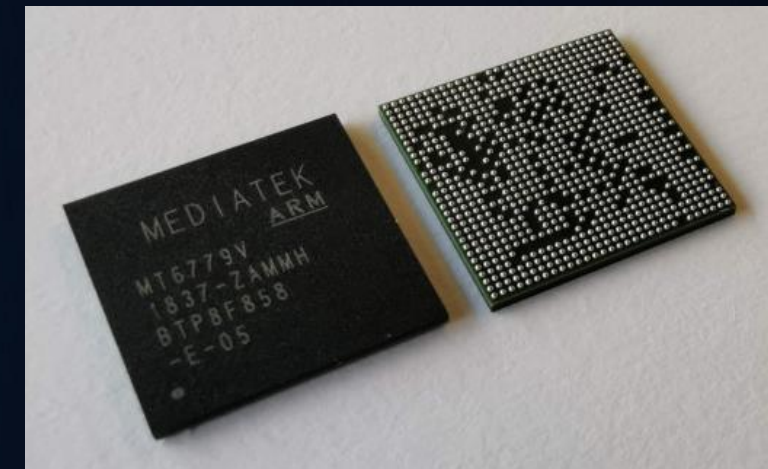
Custom designed compute and storage allow for real-time processing of data. A fully integrated cooling solution keeps components running optimally.



Challenge: Minimal Compute

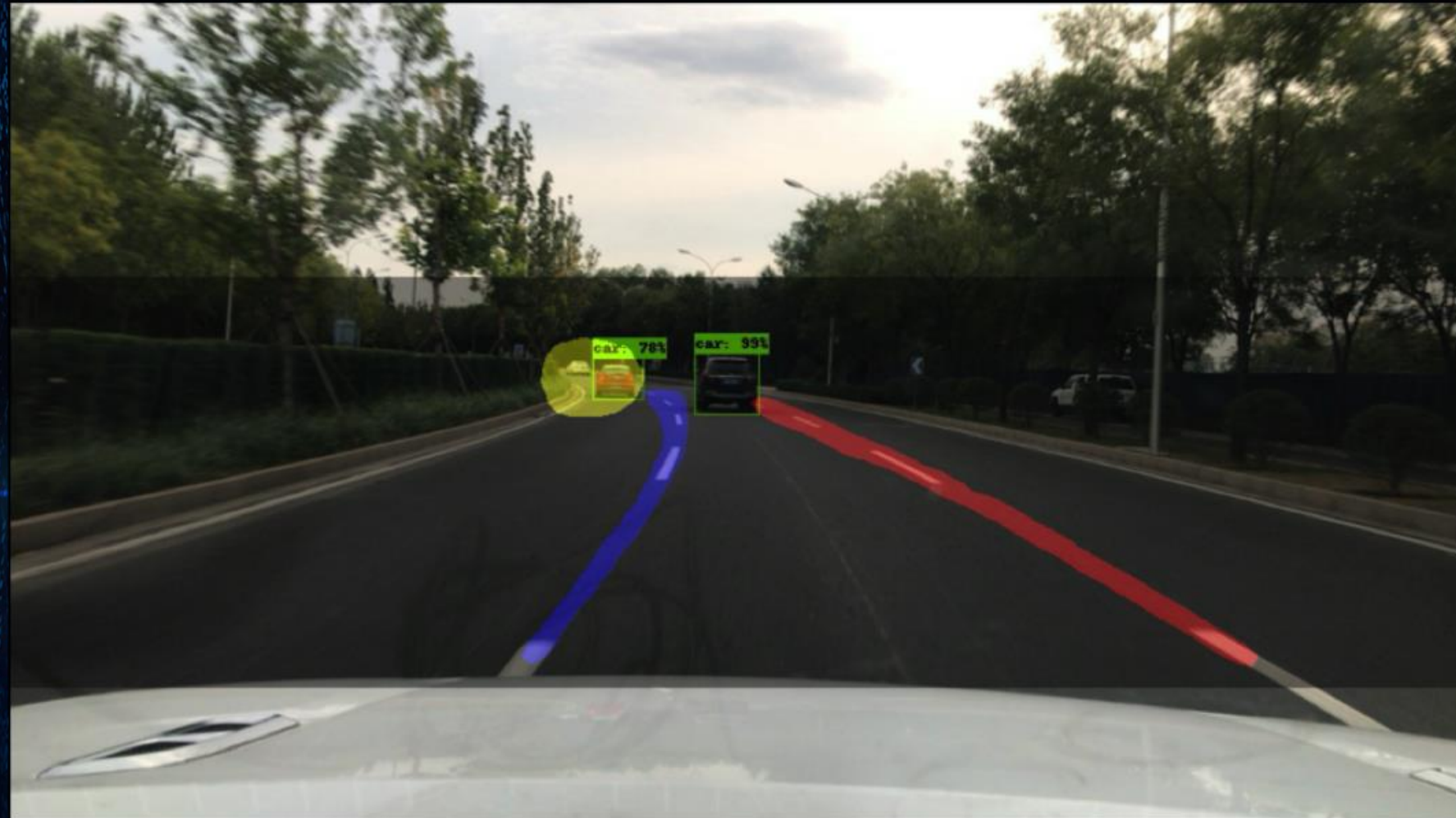


Nvidia DRIVE AGX



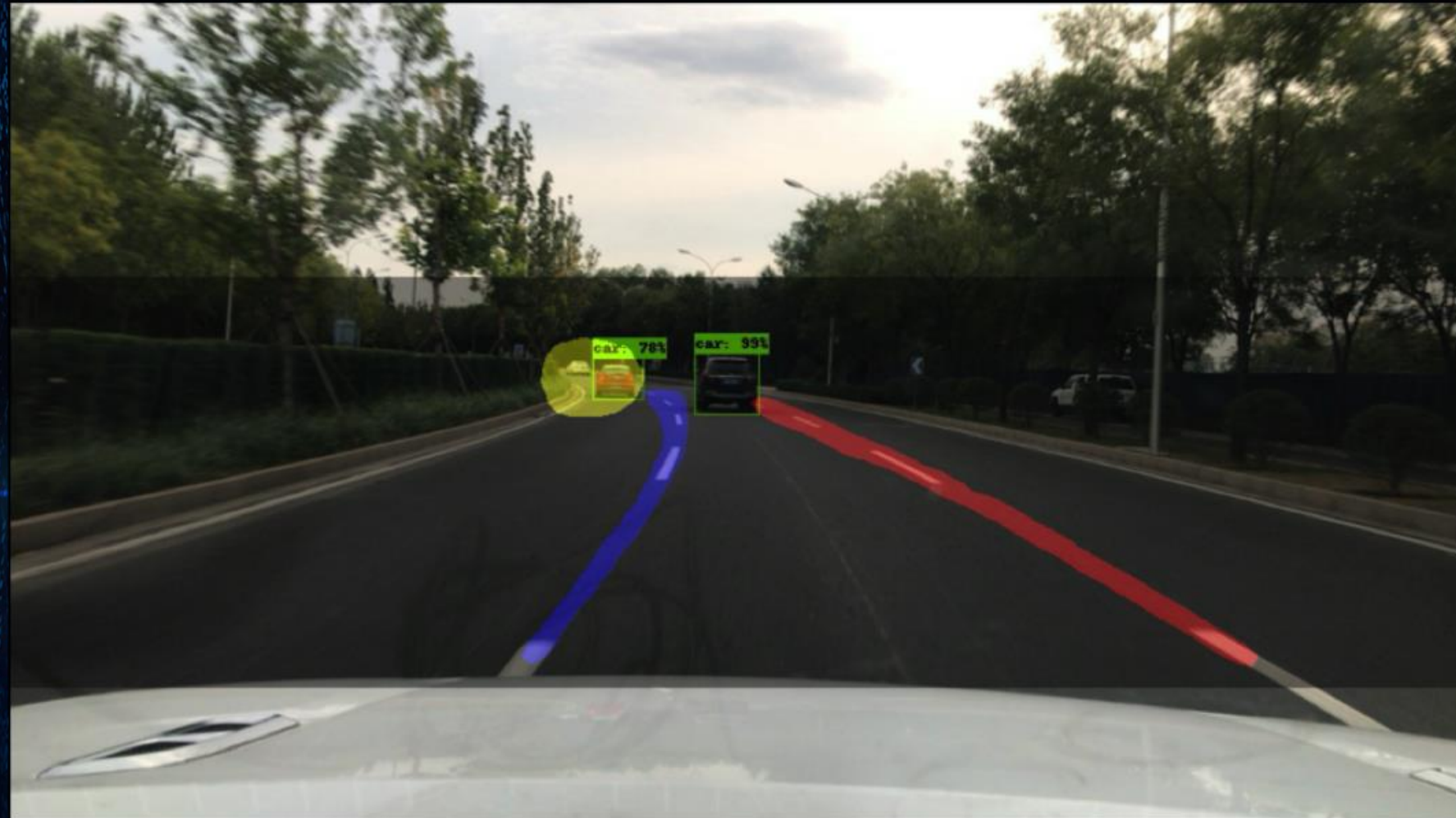
MTK8783

AR Navigation: Car Detection



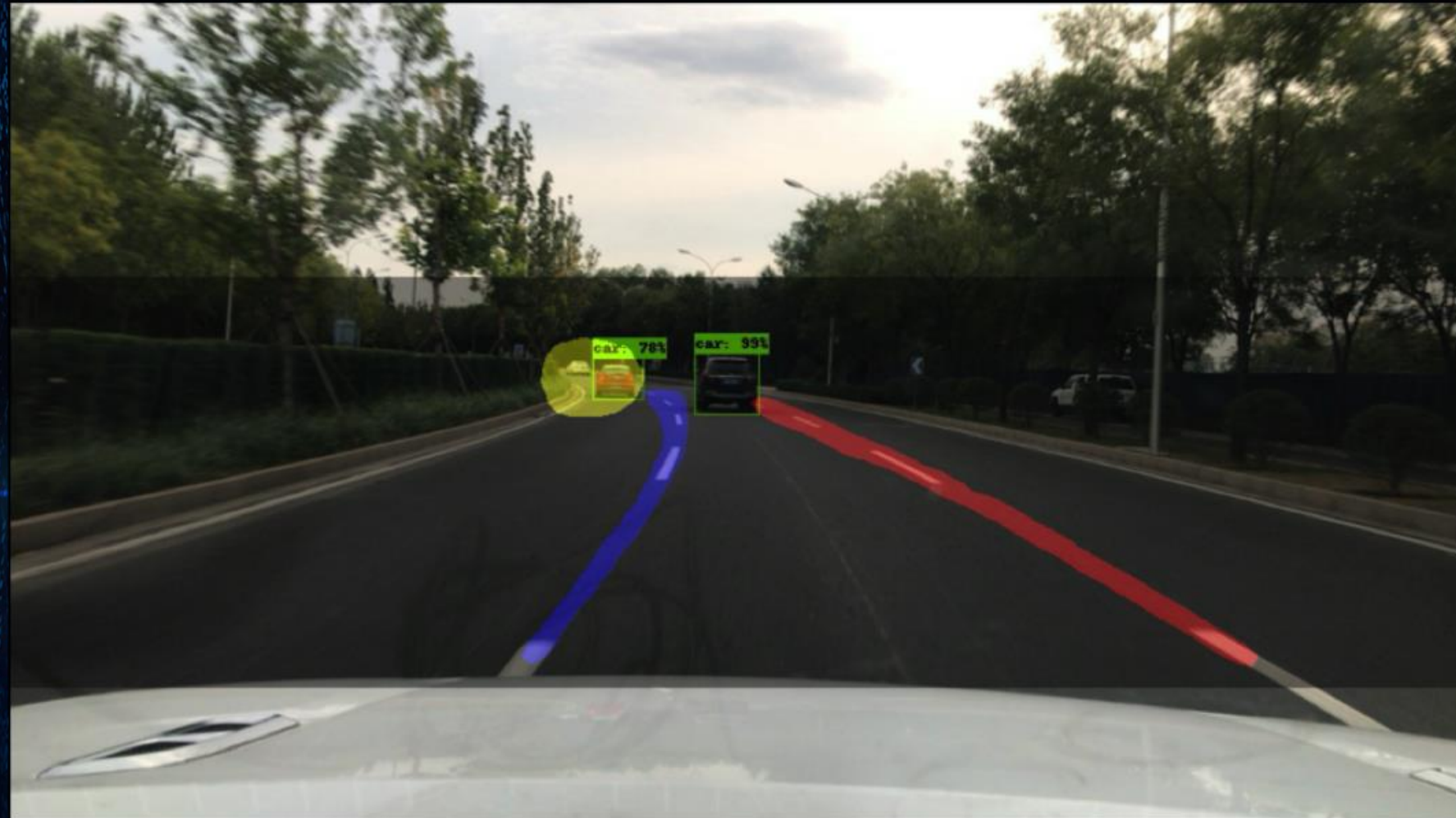
(1) model compression (2) utilize scale (3) combine with tracking

AR Navigation: Lane Boundary Detection



(1) multi-task (2) curve fitting (3) weighting and loss

AR Navigation: Direction and Location



- (1) multi-task
- (2) use segmentation for prediction
- (3) use regression to predict lane number
- (4) combine with GPS

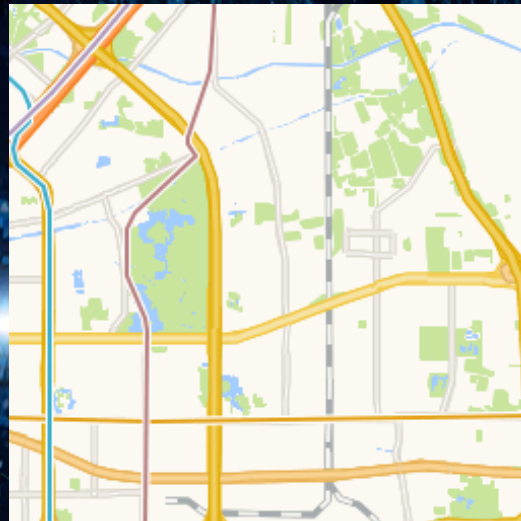
AR Navigation: Compute



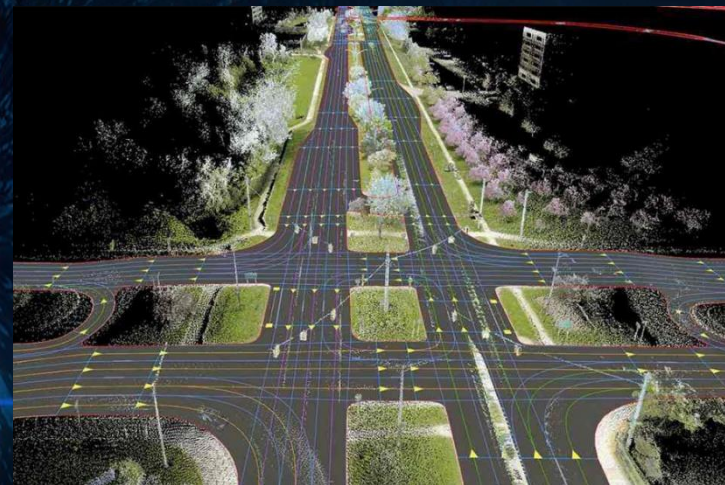
1/5 of typical smartphone

- (1) Multi-tasking model
- (2) Model compression
- (3) Optimize implementation
- (4) Balance GPU/CPU (and transfer)
- (5) Reduce context switching
- (6) ... and the rest of the system

Computer Vision @ Amap

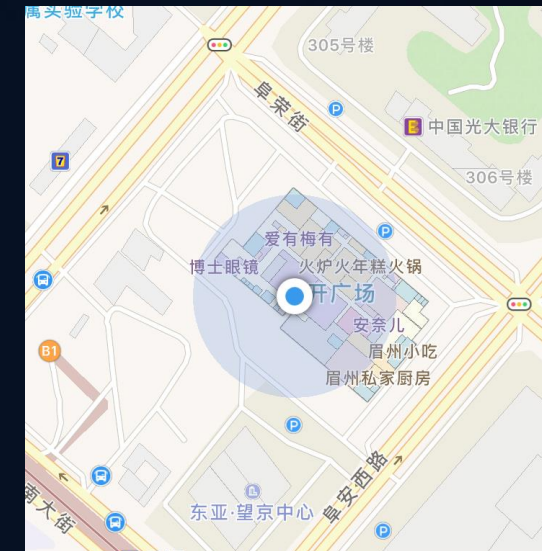


SD Map



HD Map

Mapping Automation



Location



AR Navigation

“Easy” Navigation

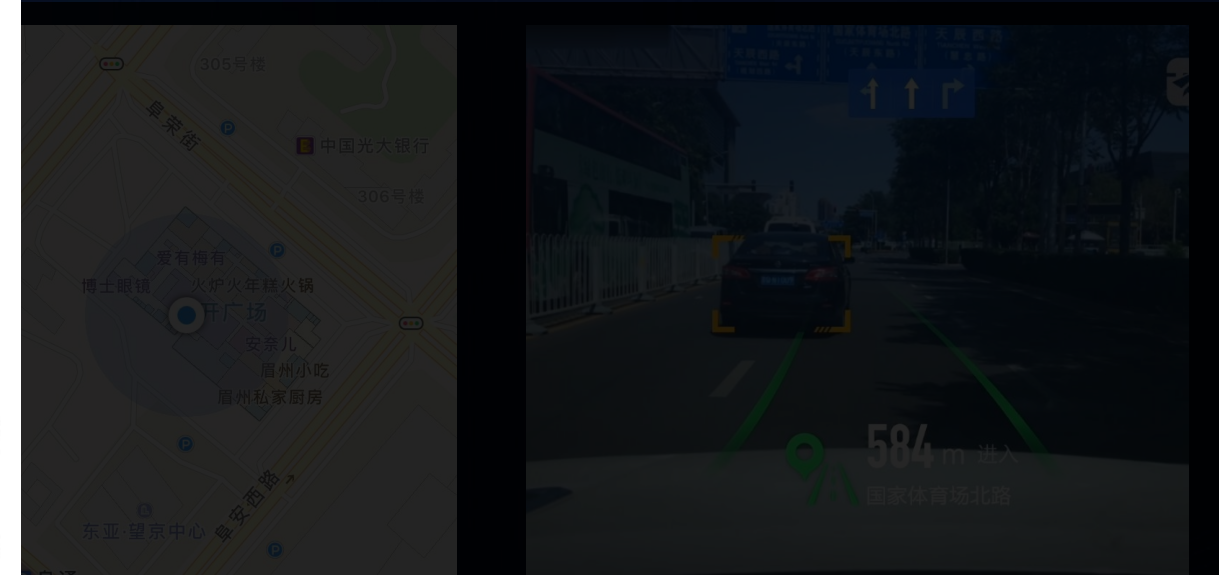
Computer Vision @ Amap

Alibaba's AutoNavi commercializes HD map by charging automakers license fee

By Robert Fri Apr 12 2019

Alibaba-backed online mapping service AutoNavi is commercializing its mapping service by charging the company's automobile partners for using its high-definition (HD) map, which is a critical piece in self-driving solutions, local financial news outlet [*Lanjinger*](#) reported.

AutoNavi is charging automakers RMB 100 (USD 15) per car per year for licensing the HD map, which captures the world with centimeter-precision whereas ordinary web map apps represents the world at a meter-level accuracy.



Location

AR Navigation

“Easy” Navigation

The Future of Mapping and Navigation

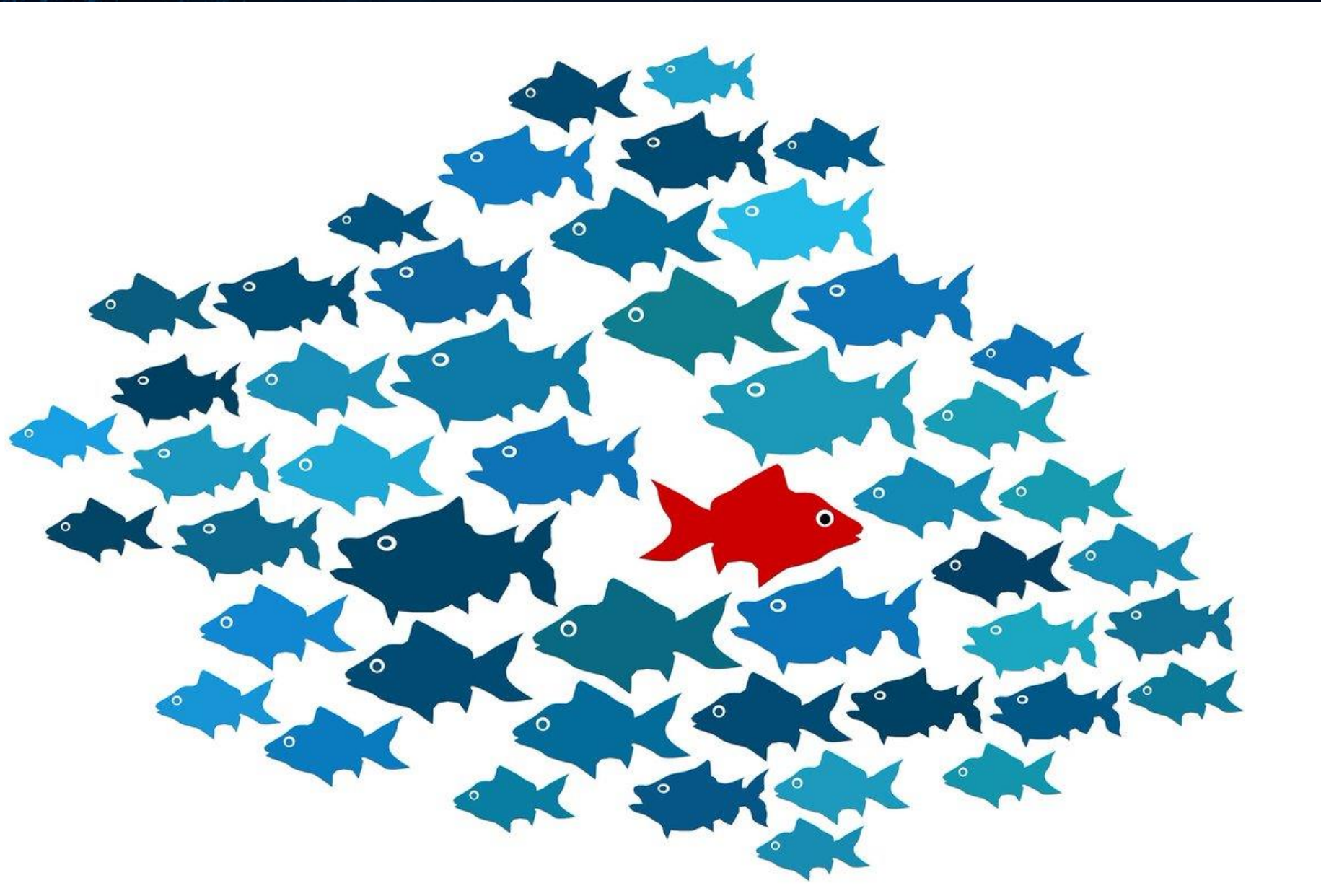


People driving cars



Machine driving cars

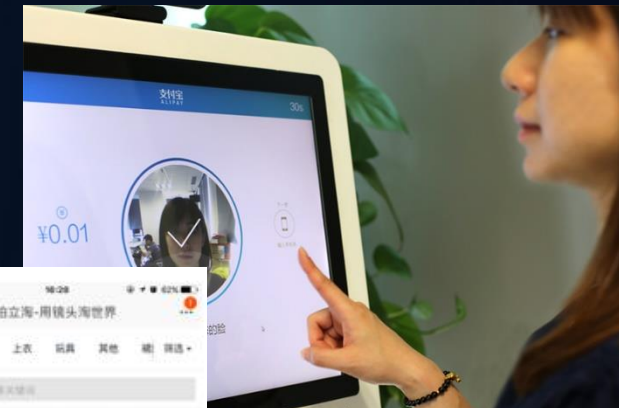
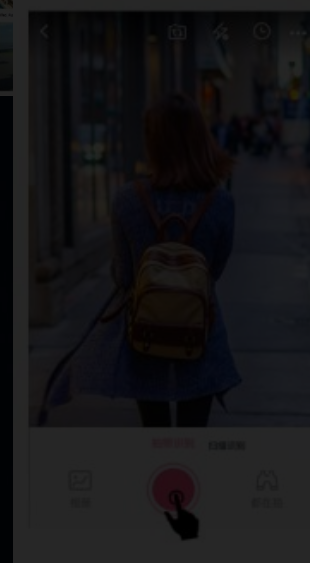
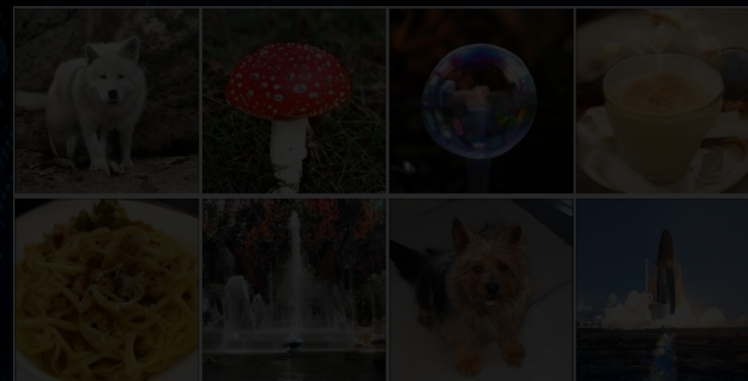
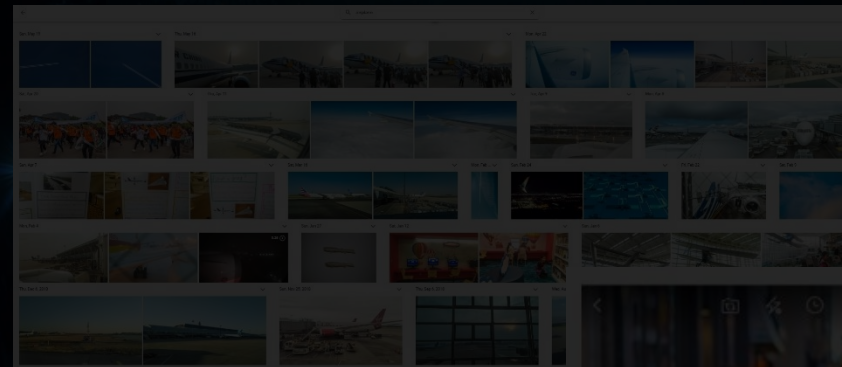
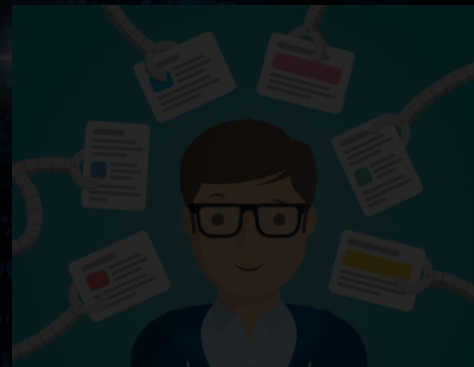
The Future of Mapping and Navigation



连接真实世界 让出行更美好

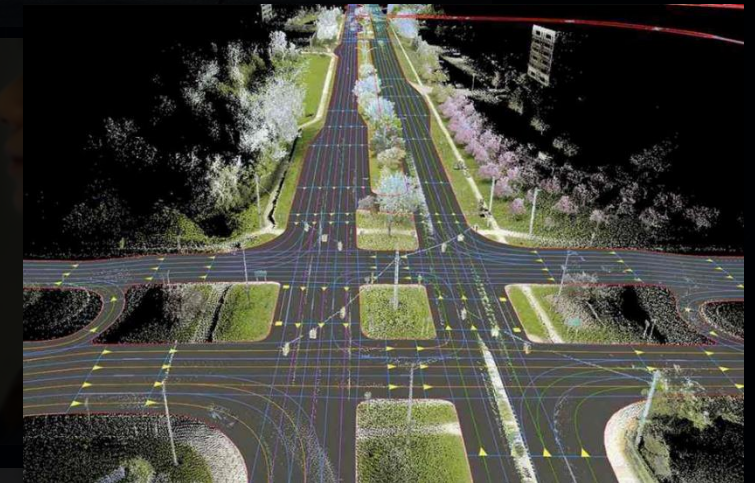
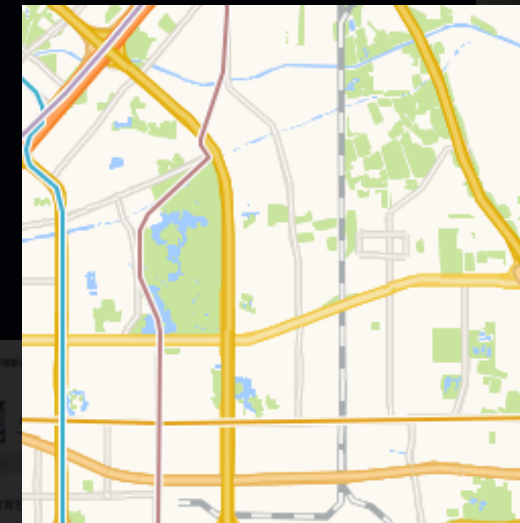
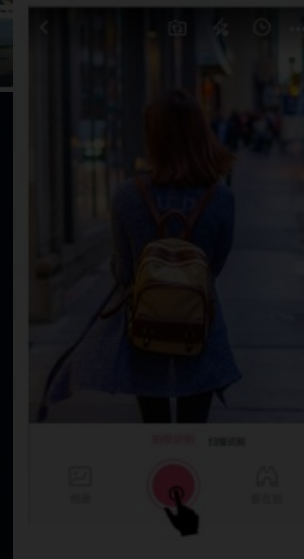
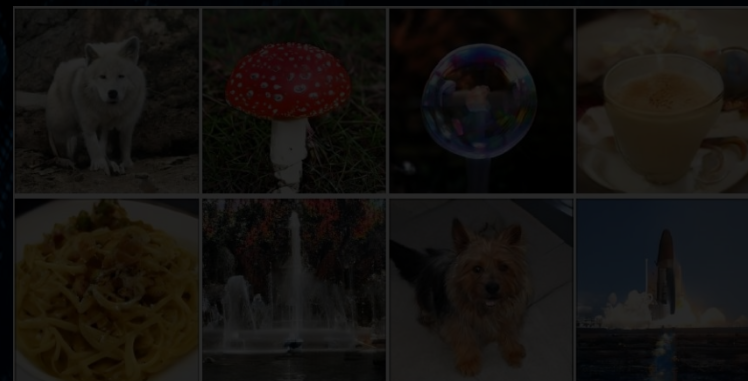
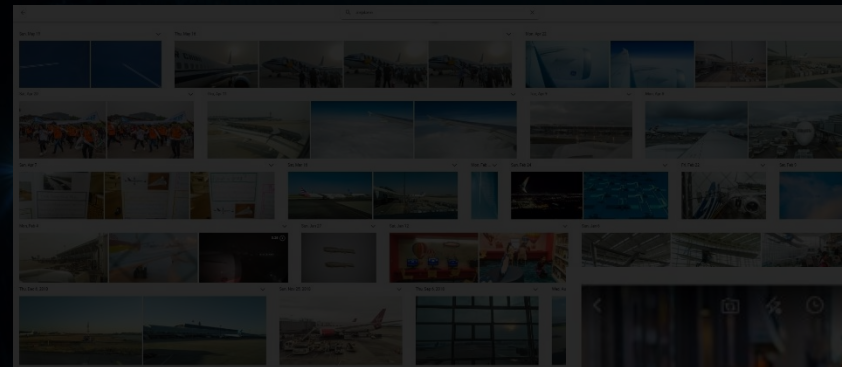
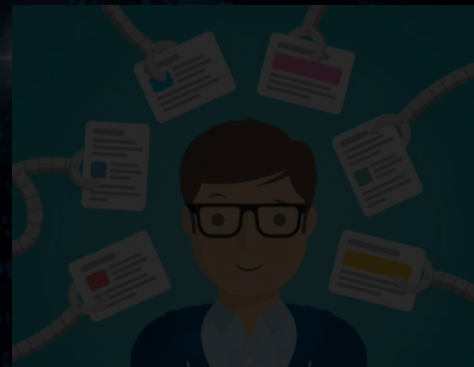
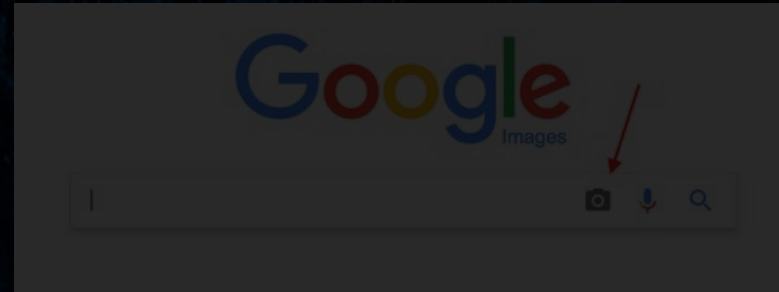
Computer Vision Applications

Cloud | Real World



Computer Vision Applications

Cloud | Real World



Thank You

